

# Joint Virtual Battlespace

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## Agenda



- JVB Overview
- JVB Support to FCS Procurement
- JVB A SMART Tool



## **JVB Description**



- JVB IS NOT A MODEL!!
- JVB is a Simulation Environment Supporting Variety of Aggregate, Entity-level and MITL/HITL Simulation Functions
- Enables the Capability to Measure the Combat Effectiveness of Information and It's use
- Tool Supporting Transformation and Acquisition Decisions in a Joint Command, Control, Communications, Computers, Intelligence, Sensors and Reconnaissance (C4ISR) Environment
- Shares Standard Algorithms, Data and Environment (Terrain, Weather)
- Supports System of System Trades and Data Collection for Analysis
- Component Based Framework Supports the FCS Concept of System of Systems
  - Shift from the Current M&S Focus on Individual Systems



### **JVB Mission**



#### **Mission:**

To Provide a Modeling and Simulation

Environment to Support Army Transformation and Army

SMART Decisions in a Joint C4ISR Framework.

#### **Current Objective:**

To Build the M&S Environment to Support Acquisition Decision for the FCS Program.



## Historical Background/ Accomplishments



- January 2001: ASA(ALT) Directed PEO IEW&S(JPSD) to Build the JVB
- October 2001: ASA(ALT) Recognized JVB's Potential to Support FCS Acquisition Process
  - Reaffirmed Army Need for JVB Capability to Support OF S&T Activities
- November 2001: Demonstrated First Instance of JVB Environment to OFTF
  - Conducted OF Survivability Study
- December 2001: FCS and TRAC Initiated Plans for C4ISR Study to Support FCS Milestone B
  - JVB Identified as a Required Capability
- Early February 2002: JVB Demonstrated to DUSA(OR)
- February 2002: JVB Adjusted Development Path and Schedule to Ensure an Instance of JVB Capability Will be in Place to Answer C4ISR Issues Proposed in the AOA
- June 2001- April 2002: Dr. Andrews, DASA-RT, Recognizes JVB on Three Occasions While Presenting Testimony to Congressional Committees



### **DASA-RT on JVB**



- Dr. Andrews, DASA-RT, Recognizes JVB on three occasions while Presenting Testimony to Congressional Committees.
  - 5 Jun 01 to Senate Armed Services Committee Subcommittee on Emerging Threats and Capabilities
  - 26 June 01 to House Armed Services Committee Subcommittee on Military Research and Development
  - 10 Apr 02 to Senate Armed Services Committee Subcommittee on Emerging Threats and Capabilities
- Advanced Simulation: ... the Joint Virtual Battlespace, (JVB) Program, is an Enabling Technology for Evaluating How FCS Contributes to the Total Capability of the Objective Force, and How the Objective Force Plays in a Joint Force. JVB, Combined With Virtual Prototyping, Also Could Provide an Effective Means for Performing Operational Test and Evaluation Without the Need for Numerous Hardware Test Articles. This Could Result in Significant Time and Financial Savings in the Army Acquisition Process.



## JVB Approach



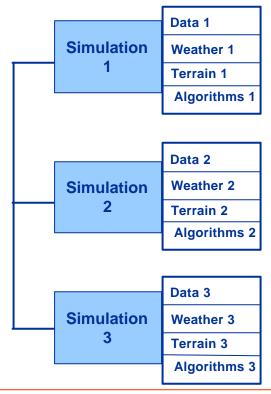
- Bring Together World Class Team of Experts
  - Government Labs
  - Army Organizations
  - Joint Representatives
  - Contractors
- Develop a Flexible, Extensible M&S Framework
- Integrate Best Available SMART Tools
- Support Objective Force Task Force, PM FCS and TRADOC to Identify Issues and Conduct Experiments
- Provide a Robust Set of Analysis Tools to Collect and Analyze Data, MOEs and MOPs
- Provide Data to PM FCS and Army Analysis Community to Support Acquisition, Force Design and Employment Decisions



## **JVB Integration Approach**

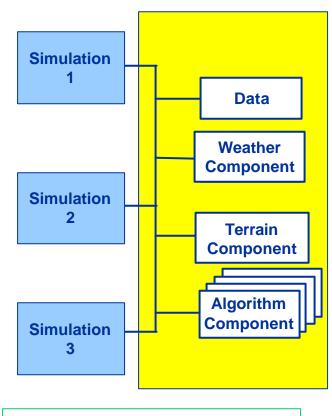


#### Current



Precoordinate to ensure everything is as Consistent as possible Post coordinate to interpret inconsistencies between models

## JVB

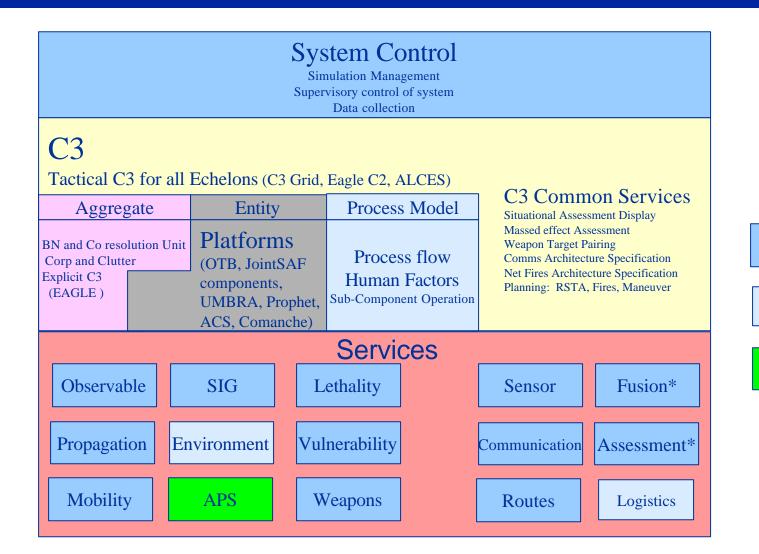


All simulations use <u>Consistent</u> data and algorithms



## **JVB Objective Software Architecture**





Available

FY 03

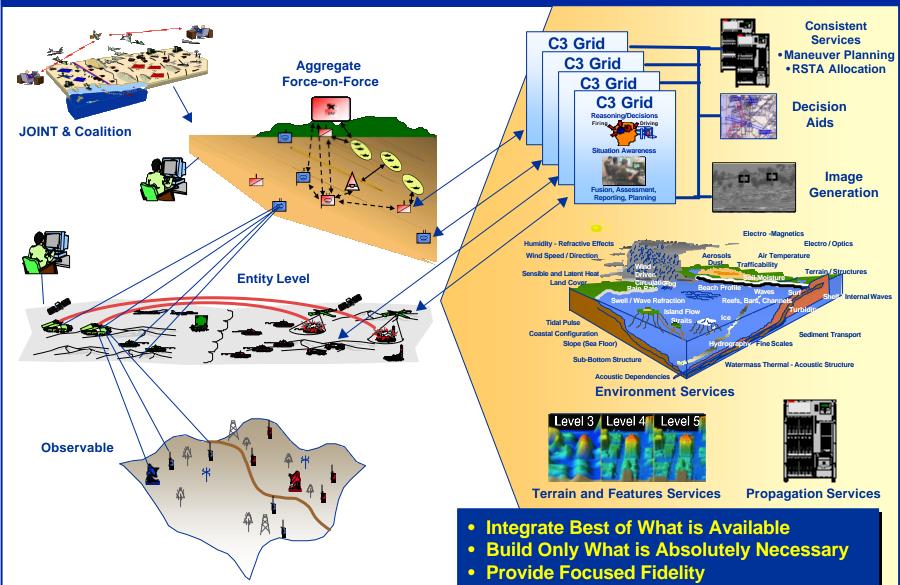
TBD

\*Limited implementation based on requirements- functional place holders until models are validated and integrated



## JVB Conceptual Framework







## Agenda



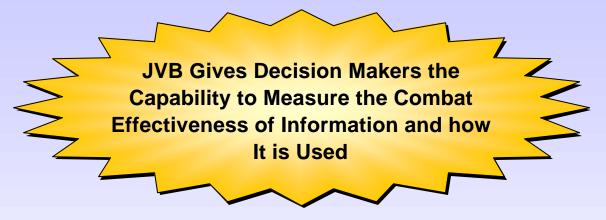
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## JVB Support for FCS C4ISR Study December 2002



Overarching Study Issue: How Does the Objective Force Commander Exercise Battle Command, Enabled by the C4ISR Architecture?



In the TRADOC-Approved Scenario, JVB Will:

- Implement FCS C4ISR Procedures and TTPs
- Collect Data Supporting Analysis of the C4ISR Procedures and TTPs
  - C4ISR Capabilities and Limits
  - Force Effectiveness
- Provide the Link for Large and Small Scale Units to Work Together in a Common Battlespace



## Unit of Action C4ISR Analysis Strategy (TRAC)

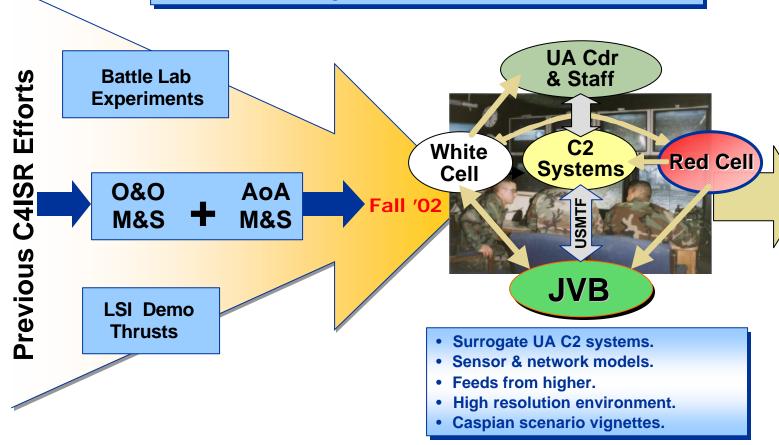


Capstone

**Experiment** 

#### **UA C4ISR Experiment Objectives**

- Serve as a Major Integrating Event for FCS/UA C4ISR O&O and OA.
- Assess CDR's Ability to Command UA.
- Assess C4ISR Capabilities to Enable the UA O&O.
- Collect DTLOMS Insights.





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## **JVB Baseline Capabilities**

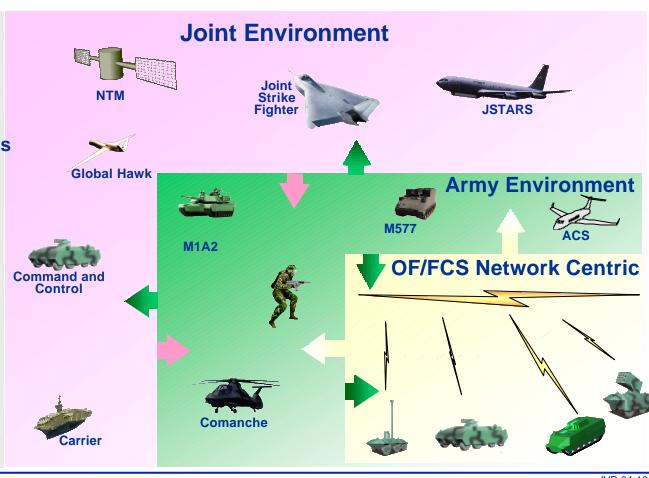


#### **SMART** (Simulation & Modeling for Acquisition, Requirements and Training)...

...Tool To Support The Objective Force and **Future Combat System** 

#### **JVB Design Includes:**

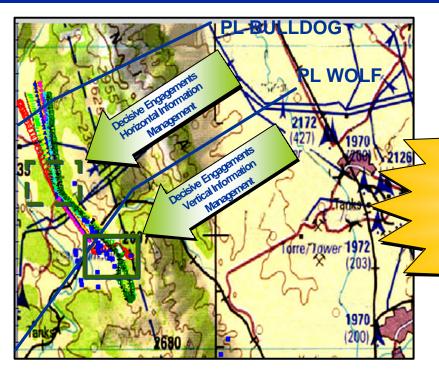
- Joint Forces
- Legacy Forces
- Objective Force
- Future Combat Systems
  - C3
  - ISR
  - Robots
  - **New Weapons**
- Logistics
- **Dynamic Weather**
- **Dynamic Terrain**
- **High Fidelity Terrain**
- Certified Data



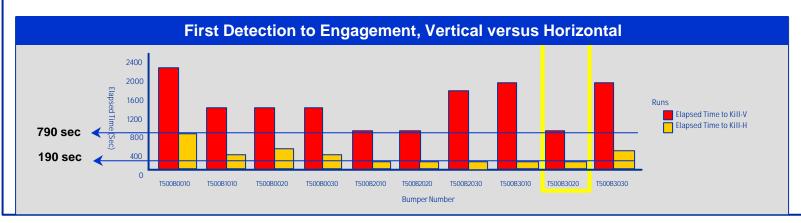


## **JVB Unique Capabilities**





Only M&S Tool That Gives
Decision Makers the Capability to
Measure the Combat
Effectiveness of Information and
It's Use Across all Echelons





## **JVB Support to Army Transformation**



- JVB Enhances Existing Army M&S to Address OF C4ISR Issues
- Integrates Existing M&S Components That can be Extended and Enhanced to Assist in the Development of AT Concepts
- JVB Will use AMSAA-Certified Performance Data & Validated Physical Models in a TRAC-Approved Scenario With TRADOC DSCINT-Approved Threat
- JVB Architecture Will Enable us to:
  - Represent Specific Communications Network Performance
  - Evaluate Various C2 Configurations and Their Dissemination of Information, its Policies and Procedures
  - Maintain Situational Awareness Down to Each Vehicle
  - Allow Commander's Input
  - Make Quick Changes for Comparison of the Effectiveness of New "FCS Like" Tactics, Techniques, and Procedures



## **Joint Virtual Battlespace Team and Partners**





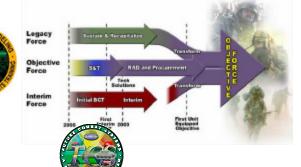
#### **MANSCEN**

- NBC Environment
- Obscurants



#### **JPSD**

- PM FCS Support
- Leverage ACTD's
- Joint C4ISR
- Integrated Analysis Tools
- Integration & Evaluation Center



Standard, Flexible, Extensible

Architecture Allows Integration

of Models from Subject Matter

**Experts to support Army** 

**Transformation** 



Joint C2 &



Simulation Support



#### **DMSO**

- HLA Standards
- Enviro, Fed



#### **AMSO**

- M&S Policy
- SMART



**AMC** 



- Terrain/Weather
- Mobility
- Seismic



#### **DOE Labs**

· Lethality/Survivability

RDEC Federation



#### **TRADOC**

- MMBL
- TRAC Ft Lee
- FPBL

## **STRICOM**

- · High Fidelity Live-Virtual-Constructive
- Semi Automated Forces



#### **Sandia National Lab**

- Robotics
- Sustainment/Reliability
- Human Factors
- Acoustics



#### **Army Research Laboratory**

- Human Workload
- Acoustics



#### **TRADOC TRAC-Leavenworth**

• Force-on-Force



- Night Vision Simulations
- Comms Model

#### Los Alamos National Lab

Force Structure

#### ASA(ALT)

- Army S&T Investment
- Guidance



#### A Common FOM



- JVB and Joint Synthetic Battlespace (JSB USAF)
  - Required to Support Acquisition of New Systems
  - Facilitate Interoperability of Joint Systems
  - HLA Based Distributed Simulation Environments
- Programs are Diverging Through Evolution of Requirements
- Facilitate Reuse and Adoption of Common Architectural Approaches
  - Component-based Architecture With Same Class Components
  - Aerial Common Sensor (ACS)/JVB Baseline Provided to JSB
- Defense Modeling and Simulation (DMSO) Sponsored Initiative to Facilitate Convergence of JVB and JSB
  - Facilitate a Truly Joint Interoperable Simulation Environment.
  - Focus on a Common Federation Object Model (FOM) ACS
  - Common Approach
  - Common Set of Tools
  - Integration of Simulation Components of Both Systems
- Will Serve as the Foundation for Joint/Coalition Interoperability (Joint Distributed Engineering Plant (JDEP) and the Coalition Interoperability Simulation Environment (CISE)



## **Future of JVB**



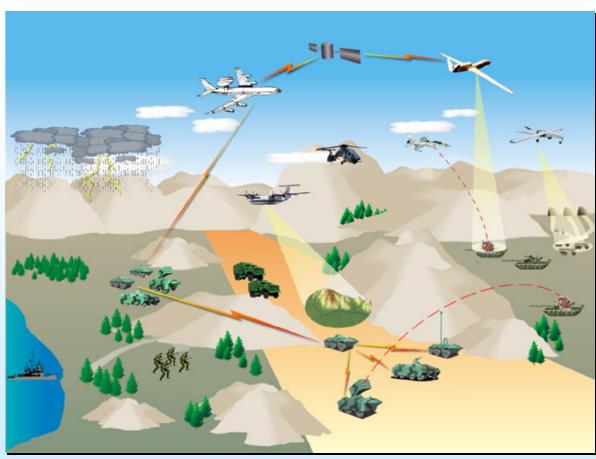
#### • JVB Will:

- Support Army Transformation Acquisition Decisions
- Provide Authoritative Joint C4ISR Environment for Acquisition,
   Analysis and Experimentation
- Provide Flexible Environment to Integrate Test and Evaluation Models
- Support Requirements, Technical Tradeoffs (What-If Analyses to provide insight for S&T investments) and Interoperability
   Studies
- Support O&O and TTP Development



### JVB Value to the Warfighter





- Accelerates
   Fielding of Obj.

   Force Systems
- Enables Joint Interoperability (System of Systems)
- Underscores
   Warfighter's Logistic
   Challenge (Tooth to
   Tail Ratio)

#### Architecture Provides

- Common Synthetic Battlespace
- Component Based Environment
- Information Driven

#### Reduces Development Time

- Integrate Mature Technologies
- Early Experimentation
- Requirements Development
- CONOPS/TTPs Refinement
- Trade-Off Studies

#### Enhances Quality

- Re-use Partners' Authoritative Models
- Early Concept Evaluation in Realistic Environment
- Flexibility For System Modifications

#### Reduces Costs

- Engineering Design Through Simulation
- Streamline Development Process



## **JVB Summary**



## Focused to Meet Objective Force and Future Combat System Schedule and Milestones

- Experiments Provide Data Supporting Analysis of Critical Army Issues
  - Use of information in the battlespace
  - Force Structure
  - Equipment Benefit to Warfighter
  - How to Fight with New Equipment
  - Logistics Impacts
- Only Army Architecture Designed to Support Network Centric Warfare Experiments and Evaluation from JTF to Individual Systems





	JVB Component	Functionality
Simulation Management and Analysis	hlaControl	Creates and manages federation execution
	Scenario Definition	Generates the scenario file used by hlaControl to initiate a JVB scenario run
		Data management system used to collect, store, retrieve and playback federation
	hlaResults	data
	Analysis Tool (hlaEval)	Analyzes simulation results; supports build, store and display results of queries
	FCSView	Provides a 3-D visualization of a federation execution including terrain features, entities, sensor area of interest (AOI), detections, routes, and detonations
	Command and Control View (C2View)	Provides a plan view display or graphical, two-dimensional view, including object state data, of a federation execution



Tactical Command, Control and Communications (C3)



Grid Java RTI Framework  Provides an abstraction layer between the federate application logic and the RT  Models C2 node process, bridging OTB and Eagle, by translating Eagle unit tas into platform commands  The Battalion Federate [Tactical Unit of Action (TUoA)]  Issues high-level C2 tasking to Company federate  [Operational Unit Cell (OUC)]  Acts directly or tasks platoon units in response to situation or Battalion direction  Responds to situation state and Company direction in controlling the behavior of
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[Functional Unit Cell (FUC)] platform and lower level entities
Aggregate Definition Service Creates and reports a perceived operational picture of variable quality that prov
(ADS) the context for C2 decisions implemented in the echelon based federates
Message Transceiver Service
(MTS) Models radio communications for the federation execution
Human Performance Model
(HPM)* Tracks and analyzes the human response to activity occurring within the C3 Gri
Dynamic Organization Service
(DOS) Describes tactical organizations by command and functional structures
Battlefield Geometry Service Generates battlefield geometry objects representing a given area or a segment,
(BGS) simulated field of view, Area of Interest (AOI), and battlefield lines  As a component of the targeting process, optimizes the weapons/target mix bas
Networked Fire Service (NFS)  As a component of the targeting process, optimizes the weapons/target hirx base on cost/benefit, timeliness, and weapon effectiveness
Organic Connection Service (OCS) Translates between groups of component interactions, providing an abstraction layer between C3 Grid component interactions and the rest of the architecture
(OCS) Tayer between CS Grid component interactions and the rest of the architecture
Mobility Server (NRMM) * Provides NRMM based limitations of ground platform speeds
Route Planning Service (RPS) * Provides NRMM based limitations of ground platform speeds





	JVB Component	Functionality
	Eagle	Models operational-level ground and air-ground combat operations using aggregate-level military units and explicitly representing C2 processes
	System Laydown and Emitter (SLE)	A pseudo-disaggregation model that publishes platforms, radios, and radars based on Eagle aggregate units
	One Semi-Automated-Forces (ONESAF) Testbed Baseline (OTB)	Creates and controls platform entities on the simulated battlefield
	UMBRA *	Models unmanned ground vehicle (UGV) and unmanned aerial vehicle (UAV) platforms
	Remote Piloted Vehicle (RPV) *	human control interface for a representative simulated Tactical UAV (TUAV) system providing both pre-mission planning and tactical situational awareness
Platforms	Rogue Warrior *	Human-in-the-loop extension of FCSView
Platí	Observable Server *	Provides observable signature data for all platforms in the JVB federation





	JVB Component	Functionality
mulation Services	Acoustic/Seismic Propagation *	Provides sound radiation and vibration frequencies between federation objects (represented sensors, emitters, and target platforms) to each respective sensor component
	EO/IR Propagation *	Computes the propagation of entity emissions to a specific call of sensor systems
	RF Propagation *	Provides IMINT/ELINT/COMINT radio frequency links between simulated objects representing sensors, emitters, and target platforms
	Acoustic Sensor *	Models acoustic sensor behavior
	Seismic Sensor *	Models seismic sensor behavior
	EO/IR Sensor *	Models electro-optical and infrared sensor behavior
	RF Sensor *	Models IMINT, ELINT, and COMINT sensor behavior
	Paint the Night (PTN) *	Provides a high resolution EO/IR scene of a target vehicle as input to a sensor system display for human-in-the-loop consideration





Ì		JVB Component	Functionality
		Nuclear, Chemical, Biological,	
		Radiological (NCBR) *	Models NCBR effects
		Lethality/Vulnerability Server *	Generates damage reports for every weapon fire / detonation event pair
	cts	· · · · · · · · · · · · · · · · · · ·	
	Effe	Missile Server *	Performs RFWSS/IDF A AS based missile behavior modeling
	Effects	Missile Server *	Performs BEWSS/IDEAAS based missile behavior modeling